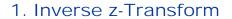
Chapter 6 z-Transform



Inverse z-Transform



- Inverse z-Transform
- z-Transform Properties
- Computation of the Convolution Sum of Finite-Length Sequences





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- 1.1 General Expression
- * Inverse z-Transform by Lookup Table
- 1.2 Inverse z-Transform by Partial-Fraction Expansion
- 1.3 Partial-Fraction Using MATLAB
- 1.4 Inverse z-Transform via Long Division
- 1.5 Inverse z-Transform Using MATLAB



1.1 General Expression

• Recall that, for $z=re^{j\omega}$, the z-transform G(z) given by

$$G(z)|_{z=re^{j\omega}} = G(re^{j\omega}) = \sum_{n=-\infty}^{\infty} g[n]r^{-n}e^{-j\omega n}$$

is merely the DTFT of the modified sequence $g[n]r^n$

• Accordingly, the inverse DTFT is thus given by

$$g[n]r^{-n} = \frac{1}{2\pi} \int_{-\pi}^{\pi} G(re^{j\omega})e^{j\omega n} d\omega$$



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1.1 General Expression

• The contour integral can be evaluated using the Cauchy's residue theorem resulting in

$$g[n] = \sum \left[\text{residues of } G(z)z^{n-1} \text{ at the poles inside } c \right]$$

$$= -\sum \left[\text{residues of } G(z)z^{n-1} \text{ at the poles outside } c \right]$$
only if there are any higher-order poles inside } c

- \Box The above equation needs to be evaluated at all values of n.
- □ Difficult to arrive at a closed-form answer in most cases.





• By making a change of variable $z=re^{j\omega}$, the previous equation can be converted into a contour integral given by

$$g[n] = \frac{1}{2\pi j} \oint_{c} G(z) z^{n-1} dz$$

where c is a counterclockwise contour of integration defined by |z| = r

• But the integral remains unchanged when c is replaced with any contour c' encircling the point z=0 in the ROC of G(z)

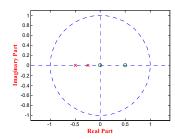


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1.1 General Expression

Example:

$$G(z) = \frac{1 - 0.5z^{-1}}{1 + 0.75z^{-1} + 0.125z^{-2}}$$
 Ze



Zeros:
$$z = 0$$
 $z = 0.5$
Poles: $z = -0.5$ $z = -0.25$

Three ROCs:

$$|z| < 0.25$$

 $0.25 < |z| < 0.5$
 $|z| > 0.5$



1.1 General Expression

$$G(z)z^{n-1} = \frac{(z-0.5)z^n}{(z+0.5)(z+0.25)}$$

Case 1: |z| < 0.25

If $n \ge 0$, there is no poles inside c. Thus, g[n] = 0 when $n \ge 0$

If n < 0, there is an |n|-order pole at z=0 which is inside c. In this case, we can compute the summation of the residues outside c instead of that inside

$$g[n] = -\{\text{Res}\{z = -0.5\} + \text{Res}\{z = -0.25\}\}$$

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1.1 General Expression

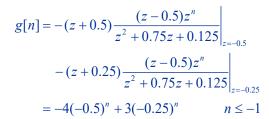
Case 2: 0.25 < |z| < 0.5

If $n \ge 0$, there is only one pole at z = -0.25 inside c

$$g[n] = (z + 0.25) \frac{(z - 0.5)z^n}{z^2 + 0.75z + 0.125} \bigg|_{z = -0.25}$$
$$= -3(-0.25)^n \qquad n \ge 0$$

1.1 General Expression





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1.1 General Expression



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If n < 0, there are one first-order pole at z = -0.25 and one |n|th-order pole at z = 0 inside c, respectively. Thus, we can compute the summation of the residues outside c instead of that inside

$$g[n] = -(z+0.5) \frac{(z-0.5)z^n}{z^2 + 0.75z + 0.125} \Big|_{z=-0.5}$$
$$= -4(-0.5)^n \qquad n \le -1$$

Hence, we can rewrite g[n] as follows

$$g[n] = -3(-0.25)^n u[n] - 4(-0.5)^n u[-n-1]$$



1.1 General Expression

Case 3: |z| > 0.5

If $n \ge 0$, there are two first-order poles at z = -0.25 and z = -0.5 inside c

$$g[n] = (z+0.5) \frac{(z-0.5)z^n}{z^2 + 0.75z + 0.125} \bigg|_{z=-0.5}$$
$$+ (z+0.25) \frac{(z-0.5)z^n}{z^2 + 0.75z + 0.125} \bigg|_{z=-0.25}$$
$$= 4(-0.5)^n - 3(-0.25)^n \qquad n \ge 0$$

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1.2 Inverse z-Transform by Partial-Fraction Expansion



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- A rational z-transform G(z) with a causal inverse transform g[n] has an ROC that is exterior to a circle
- Here it is more convenient to express G(z) in a partial-fraction expansion form and then determine g[n] by summing the inverse transform of the individual simpler terms in the expansion

1.1 General Expression



If n<0, there are two first-order poles and one |n|th-order pole at z=-0.25, z=-0.25 and z=0 inside c, respectively. Thus, we can compute the summation of the residues outside c instead of that inside. Because there is no poles outside c. Thus, g[n]=0 in this case

Summary:

$$g[n] = \begin{cases} -4(-0.5)^n u[-n-1] + 3(-0.25)^n u[-n-1], & |z| < 0.25 \\ -3(-0.25)^n u[n] - 4(-0.5)^n u[-n-1], & 0.25 < |z| < 0.5 \\ 4(-0.5)^n u[n] - 3(-0.25)^n u[n], & |z| > 0.5 \end{cases}$$

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1.2 Inverse z-Transform by Partial-Fraction Expansion



• A rational G(z) can be expressed as

$$G(z) = \frac{P(z)}{D(z)} = \sum_{i=0}^{M} p_i z^{-i} / \sum_{i=0}^{N} d_i z^{-i}$$

• If then G(z) can be re-expressed as

$$G(z) = \sum_{\ell=0}^{M-N} \eta_{\ell} z^{-\ell} + \frac{P_{1}(z)}{D(z)}$$
 Proper Fraction (真分数)

where the degree of $P_1(z)$ is less than N



• Rational G(z)

$$G(z) = \sum_{\ell=0}^{M-N} \eta_\ell z^{-\ell} + \frac{P_1(z)}{D(z)}$$

• Then

$$\sum_{\ell=0}^{M-N} z^{-\ell} \longleftrightarrow \sum_{\ell=0}^{M-N} \delta[n-\ell]$$

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1.2 Inverse z-Transform by Partial-Fraction Expansion



- Rational $G(z) = \sum_{\ell=0}^{M-N} \eta_{\ell} z^{-\ell} + \frac{P_1(z)}{D(z)}$
- For simple poles, let

$$H(z) = \frac{P_1(z)}{D(z)} = \sum_{\ell=0}^{N} \left(\frac{\rho_{\ell}}{1 - \lambda_{\ell} z^{-1}} \right) \longleftrightarrow \sum_{\ell=0}^{N} \rho_{\ell} (\lambda_{\ell})^n \mu[n]$$

poles: $\{\lambda_{\ell}\}, 1 \leq \ell \leq N$

Constants: $\rho_{\ell} = (1 - \lambda_{\ell} z^{-1}) H(z) \Big|_{z=\lambda_{\ell}}$

1.2 Inverse z-Transform by Partial-Fraction Expansion



Example 1: Determine the inverse z-transform

$$G(z) = \frac{2 + 0.8z^{-1} + 0.5z^{-2} + 0.3z^{-3}}{1 + 0.8z^{-1} + 0.2z^{-2}}$$

By long division we arrive at

$$1.5\delta[n-1]$$

$$G(z) = -3.5 + 1.5z^{-1} + \frac{5.5 + 2.1z^{-1}}{1 + 0.8z^{-1} + 0.2z^{-2}}$$

$$-3.5\delta[n]$$

1.2 Inverse z-Transform by Partial-Fraction Expansion



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Let

$$H(z) = \frac{5.5 + 2.1z^{-1}}{1 + 0.8z^{-1} + 0.2z^{-2}}$$

$$= \frac{2.75 + 0.25j}{1 - (-0.4 + 0.2j)z^{-1}} + \frac{2.75 - 0.25j}{1 - (-0.4 - 0.2j)z^{-1}}$$

$$(2.75 + 0.25j)(-0.4 + 0.2j)^{n}u[n]$$

$$(2.75 - 0.25j)(-0.4 - 0.2j)^{n}u[n]$$



- Rational $G(z) = \sum_{\ell=0}^{M-N} \eta_{\ell} z^{-\ell} + \frac{P_1(z)}{D(z)}$
- For multiple poles, let

$$H(z) = \frac{P_1(z)}{D(z)} = \sum_{\ell=0}^{N-L} \left(\frac{\rho_{\ell}}{1 - \lambda_{\ell} z^{-1}} \right) \left(\sum_{i=1}^{L} \left(\frac{\gamma_i}{(1 - \nu z^{-1})^i} \right) \right)$$

constants:

$$\gamma_{i} = \frac{1}{(L-i)!(-v)^{L-i}} \frac{d^{L-i}}{d(z^{-1})^{L-i}} [(1-vz^{-1})^{L} G(z)]|_{z=v} \quad 1 \le i \le L$$
multiple poles: v

1.2 Inverse z-Transform by Partial-Fraction Expansion



Example 2: Determine the inverse z-transform

$$H(z) = \frac{z(z+2)}{(z-0.2)(z+0.6)} = \frac{(1+2z^{-1})}{(1-0.2z^{-1})(1+0.6z^{-1})}$$

A partial-fraction expansion of H(z) is

$$H(z) = \frac{\rho_1}{1 - 0.2z^{-1}} + \frac{\rho_2}{1 + 0.6z^{-1}}$$

$$\rho_1 = (1 - 0.2z^{-1})H(z)\Big|_{z=0.2} = \frac{1 + 2z^{-1}}{1 + 0.6z^{-1}}\Big|_{z=0.2} = 2.75$$

1.2 Inverse z-Transform by Partial-Fraction Expansion



Solutions:

Step 1-- Converting G(z) into the form of proper fractions by long division

Step 2– Summing up the inverse transform of the individual simpler terms in the expansion

* Assumming that g[n] is causal

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1.2 Inverse z-Transform by Partial-Fraction Expansion



Example 2:

Now
$$H(z) = \frac{\rho_1}{1 - 0.2z^{-1}} + \frac{\rho_2}{1 + 0.6z^{-1}}$$

$$\rho_1 = (1 - 0.2z^{-1})H(z)\Big|_{z=0.2} = \frac{1 + 2z^{-1}}{1 + 0.6z^{-1}}\Big|_{z=0.2} = 2.75$$

$$\rho_2 = (1 + 0.6z^{-1})H(z)\Big|_{z=0.6} = \frac{1 + 2z^{-1}}{1 - 0.2z^{-1}}\Big|_{z=0.2} = -1.75$$



Example 2:

Hence
$$H(z) = \frac{2.75}{1 - 0.2z^{-1}} + \frac{1.75}{1 + 0.6z^{-1}}$$

Inverse transform is therefore given by

$$h[n] = 2.75(0.2)^n \mu[n] - 1.75(-1.6)^n \mu[n]$$

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1.2 Inverse z-Transform by Partial-Fraction Expansion



Example 3:

$$\frac{1}{1 - \frac{1}{2}z^{-1}} \xrightarrow{\text{IZT}} 0.36(\frac{1}{2})^{n} \mu[n] \qquad \frac{1}{1 + \frac{1}{3}z^{-1}} \xrightarrow{\text{IZT}} 0.24(-\frac{1}{3})^{n} \mu[n]$$

$$\frac{0.4}{\left(1 + \frac{1}{3}z^{-1}\right)^{2}} \xrightarrow{\text{IZT}} 0.4(n+1)(-\frac{1}{3})^{n} \mu[n]$$

$$g[n] = [0.36(\frac{1}{2})^{n} + 0.24(-\frac{1}{3})^{n} + 0.4(n+1)(-\frac{1}{3})^{n}] \mu[n]$$
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1.2 Inverse z-Transform by Partial-Fraction Expansion



Example 3: Determine the inverse z-transform

$$G(z) = \frac{z^3}{(z - \frac{1}{2})(z + \frac{1}{3})^2}, \quad |z| > \frac{1}{2}$$

A partial-fraction expansion of H(z) is

$$G(z) = \frac{0.36}{1 - \frac{1}{2}z^{-1}} + \frac{0.24}{1 + \frac{1}{3}z^{-1}} + \frac{0.4}{(1 + \frac{1}{3}z^{-1})^2}$$

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1.2 Inverse z-Transform by Partial-Fraction Expansion



• Enlargement of ROC caused by pole-zero cancellation

Consider two causal sequences g[n] and h[n], with z-transforms G(z) and H(z), respectively, as given below:

$$G(z) = \frac{2 + 1.2z^{-1}}{1 - 0.2z^{-1}}, \qquad |z| > 0.2$$

$$H(z) = \frac{3}{1 + 0.6z^{-1}}, \qquad |z| > 0.6$$



• The intersection of the two ROCs is |z| > 0.6. The product of the above two z-transforms is

$$G(z)H(z) = \left(\frac{2+1.2z^{-1}}{1-0.2z^{-1}}\right)\left(\frac{3}{1+0.6z^{-1}}\right) = \frac{6}{1-0.2z^{-1}}$$

whose ROC is given by |z| > 0.2, which is larger than the region |z| > 0.6

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1.3 Partial-Fraction Expansion Using MATLAB



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• [num,den]=residuez(r,p,c) converts a z-transform expressed in a partial-fraction expansion form to its rational form

1.3 Partial-Fraction Expansion Using MATLAB



- [r,p,c]= residuez(num,den) develops the partial-fraction expansion of a rational z-transform with numerator and denominator coefficients given by vectors num and den
 - □ Vector *r* contains the residues
 - \Box Vector p contains the poles
 - \square Vector \boldsymbol{c} contains the constants $\boldsymbol{\eta}_{l}$

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1.4 Inverse z-Transform via Long Division



- The z-transform G(z) of a causal sequence {g[n]} can be expanded in a power series in z-1 by long division
- In the series expansion, the coefficient multiplying the term z^{-n} is then the *n*-th sample g[n]
- For a rational z-transform expressed as a ratio of polynomials in z^{-1} , the power series expansion can be obtained by **long division**.

1.4 Inverse z-Transform via Long Division



Example 1:

• Consider $X(z) = \frac{1+2z^{-1}}{1+0.4z^{-1}-0.12z^{-2}}$

Long division of the numerator by the denominator yields

$$X(z) = 1 + 1.6z^{-1} - 0.52z^{-2} + 0.4z^{-3} - 0.224z^{-4} + \cdots$$

• Hence

$${x[n]}={1, 1.6, -0.52, 0.4, -0.2224,...} n \ge 0$$

1.5 Inverse z-Transform Using MATLAB



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- The function impz can be used to find the inverse of a rational z-transform G(z)
- The function computes the coefficients of the power series expansion of G(z)
- The number of coefficients can either be user specified or determined automatically

1.4 Inverse z-Transform via Long Division



Example 2:

• Consider $X(z) = \frac{z^{-1}}{(1-z^{-1})^2}$. Long division $\frac{1}{(1-z^{-1})^2} = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + ...$ Then $\frac{z^{-1}}{(1-z^{-1})^2} = z^{-1} + 2z^{-2} + 3z^{-3} + 4z^{-4} + ...$

• Hence

$$\{x[n]\} = \{0 \ 1 \ 2 \ 3 \ 4 \ ...\}, \text{ for } n \ge 0. \quad x[n] = \begin{cases} n, & n \ge 0, \\ 0, & n < 0. \end{cases}$$

2. z-Transform Properties



Useful properties of the z-transform.

Property	Sequence	z-Transform	ROC
	g[n] h[n]	G(z) H(z)	$rac{\mathfrak{R}_{_{g}}}{\mathfrak{R}_{_{h}}}$
Conjugation Time-reversal Linearity	$g^*[n]$ $g[-n]$ $\alpha g[n] + \beta h[n]$	$G*(z*)$ $G(1/z)$ $\alpha G(z) + \beta H(z)$	$\frac{\mathfrak{R}_g}{1/\mathfrak{R}_g}$ Includes $\mathfrak{R}_g \cap \mathfrak{R}_h$
Time-shifting	$g[n-n_0]$	$z^{-n_0}G(z)$	\Re_{s} except possibly the point z=0 or ∞
Multiplication by an exponential sequence	$\alpha^n g[n]$	$G(z/\alpha)$	$ lpha \mathfrak{R}_{_{g}}$



2. z-Transform Properties

Useful properties of the z-transform.				
Property	Sequence	z-Transform	ROC	
	g[n]	G(z)	\Re_g	
	h[n]	H(z)	$\mathfrak{R}_{\scriptscriptstyle h}$	
Differentiation of G(z)	ng[n]	$-z\frac{dG(z)}{dz}$	ng, except possibly the point z=0 or ∞	
Convolution	g[n]*h[n]	G(z)H(z)	Includes $\mathfrak{R}_{_g}\cap\mathfrak{R}_{_h}$	
Modulation	g[n]h[n]	$\frac{1}{2\pi j} \oint_C G(v) H(z/v) v^{-1}$	^{-1}dv Includes $\mathfrak{R}_{g}\mathfrak{R}_{h}$	
Parseval's $\sum_{n=-\infty}^{\infty} g[n]h^*[n] = \frac{1}{2\pi j} \oint_{C} G(v)H^*(1/v^*)v^{-1}dv$ 37				

2. z-Transform Properties



 Using the differentiation property, we arrive at the z-transform of nx[n] as

$$-z\frac{dX(z)}{dz} = \frac{\alpha z^{-1}}{(1-\alpha z^{-1})^2} \quad |z| > |\alpha|$$

• Using the linearity property we finally obtain

$$Y(z) = \frac{1}{\left(1 - \alpha z^{-1}\right)^2} \left|z\right| > \left|\alpha\right|$$

2. z-Transform Properties



Example 1:

$$y[n] = (n+1)\alpha^n u[n]$$

y[n] can be rewritten as y[n] = nx[n] + x[n]where $x[n] = \alpha^n u[n]$

• The z-transform of x[n] is given by

$$X(z) = \frac{1}{1 - \alpha z^{-1}} |z| > |\alpha|$$

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2. z-Transform Properties



Example 2:

$$x[n] = r^n \cos(\omega_0 n) \mu[n]$$

x[n] can be rewritten as x[n] = v[n] + v*[n]where $v[n] = \frac{1}{2}r^n e^{j\omega_0 n} \mu[n] = \frac{1}{2}\alpha^n \mu[n]$

•The z-transform of x[n] is given by

$$V(z) = \frac{1}{2} \cdot \frac{1}{1 - \alpha z^{-1}} = \frac{1}{2} \cdot \frac{1}{1 - r e^{j\omega_0} z^{-1}}, \quad |z| > |\alpha| = r$$

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2. z-Transform Properties

Using the conjugation property we obtain the z-transform of $v^*[n]$ as

$$V^*(z^*) = \frac{1}{2} \cdot \frac{1}{1 - \alpha^* z^{-1}} = \frac{1}{2} \cdot \frac{1}{1 - re^{-j\omega_0} z^{-1}}, \quad |z| > |\alpha| = r$$

Thus
$$X(z) = V(z) + V^*(z^*)$$

$$= \frac{1}{2} \left(\frac{1}{1 - re^{j\omega_0} z^{-1}} + \frac{1}{1 - re^{-j\omega_0} z^{-1}} \right),$$

$$= \frac{1 - (r\cos\omega_0)z^{-1}}{1 - (2r\cos\omega_0)z^{-1} + r^2 z^{-2}} \qquad |z| > r$$

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2. z-Transform Properties

Example 4:

Determine the energy of the sequence

$$x[n] = a^n u[n], \qquad 0 < a < 1$$

Using the Parseval's relation

$$\xi_{x} = \frac{1}{2\pi i} \oint_{c} X(v) X(v^{-1}) v^{-1} dv$$

Therefore

$$\frac{1}{2\pi j} \oint_c X(z)X(z^{-1})z^{-1}dz = [\text{sum of residues of } X(z)X(z^{-1})z^{-1} \text{ inside } c]$$

2. z-Transform Properties

Example 3:

Determine the z-transform V(z) of the sequence v[n]

$$d_0v[n] + d_1v[n-1] = p_0\delta[n] + p_1\delta[n-1] \qquad |d_1/d_0| < 1$$

We have

$$d_0V(z) + d_1z^{-1}V(z) = p_0 + p_1z^{-1}$$

Therefore

$$V(z) = \frac{p_0 + p_1 z^{-1}}{d_0 + d_1 z^{-1}}$$

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2. z-Transform Properties



Example 4:

The ZT is given by $X(z) = \frac{1}{1 - \alpha z^{-1}}, |z| > \alpha$.

Then
$$X(z)X(z^{-1})z^{-1} = \frac{z^{-1}}{(1-\alpha z^{-1})(1-\alpha z)} = \frac{1}{(z-\alpha)(1-\alpha z)}$$

It has a pole at $z=\alpha$ inside the unit circle

residue =
$$\frac{1}{1-\alpha z}\Big|_{z=\alpha} = \frac{1}{1-\alpha^2}$$
 $\xi_x = \frac{1}{1-\alpha^2}$

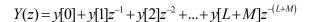
3. Computation of the Convolution Sum of Finite-Length Sequences



- Linear Convolution using Polynomial Multiplication
- Circular Convolution using Polynomial Multiplication

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3.1 Linear Convolution



 \square Polynomials in z^{-1} of degree L+M

• Coefficients of the polynomial are precisely the samples of the sequence.

n-th coefficient of Y(z)

$$y[n] = \sum_{k=0}^{L+M} x[k]h[n-k]$$

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3.1 Linear Convolution



• For length-L+1 and length-M+1 sequence x[n] and h[n]

$$X(z) = x[0] + x[1]z^{-1} + x[2]z^{-2} + \dots + x[L]z^{-L}$$

$$H(z) = h[0] + h[1]z^{-1} + h[2]z^{-2} + \dots + h[M]z^{-M}$$

 \square Polynomials in z^{-1} of degree L and M

• From the convolution theorem:

$$y_L[n] = x[n] * h[n] \longleftrightarrow Y(z) = H(z)X(z)$$

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3.1 Linear Convolution



Example 1:

• Linear convolution of Right-Sided Sequences $x[n] = \{-2, 0, 1, -1, 3\}$ $h[n] = \{1, 2, 0, 1\}$ using the Polynomial Multiplication Method $X(z) = -2 + z^{-2} - z^{-3} + 3z^{-4}$ $H(z) = 1 + 2z^{-1} - z^{-3}$ $Y(z) = X(z)H(z) = (-2 + z^{-2} - z^{-3} + 3z^{-4})(1 + 2z^{-1} - z^{-3})$

$$Y(z) = X(z)H(z) = (-2+z^{-2}-z^{-3}+3z^{-4})(1+2z^{-1}-z^{-3})$$

$$= -2-4z^{-1}+z^{-2}+3z^{-3}+z^{-4}+5z^{-5}+z^{-6}-3z^{-7}$$

$$y[n] = \{-2, -4, 1, 3, 1, 5, 1, -3\}$$



3.1 Linear Convolution

Example 2:

• Linear convolution of Two-Sided Sequences

$$x[n] = \{3, -2, 4\}$$
 $h[n] = \{4, 2, -1\}$

$$n[n] = \{4, 2, -1\}$$

using the Polynomial Multiplication Method

$$X(z) = 3z - 2 + 4z^{-1}$$

$$X(z) = 3z - 2 + 4z^{-1}$$
 $H(z) = 4 + 2z^{-1} - z^{-2}$

$$Y(z) = X(z)H(z) = (3z-2+4z^{-1})(4+2z^{-1}-z^{-3})$$

$$= 12z-2+9z^{-1}+10z^{-2}-4z^{-3}$$

$$y[n] = \{12, -2, 9, 10, -4\}$$

3.2 Circular Convolution

• For length-N causal sequences x[n] and y[n], $0 \le n \le N-1$

$$X(z) = x[0] + x[1]z^{-1} + x[2]z^{-2} + ... + x[N-1]z^{-(N-1)}$$

$$H(z) = h[0] + h[1]z^{-1} + h[2]z^{-2} + ... + h[N-1]z^{-(N-1)}$$

- \square Polynomials in z^{-1} of degree N-1
- From the convolution definition:

$$Y_L(z) = y_L[0] + y_L[1]z^{-1} + y_L[2]z^{-2} + ... + y_L[2N - 2]z^{-(2N - 2)}$$

$$Y_C(z) = \langle Y_L(z) \rangle_{(z^{-N}-1)}$$



3.2 Circular Convolution



• The circular convolution can also be related to polynomial multiplication but requires a modulo operation after the multiplication.

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3.2 Circular Convolution



Example 1:

- Circular convolution of causal sequences g[n] and h[n]
- $(0 \le n \le 3)$ using the Polynomial Multiplication Method.

$$G(z) = g[0] + g[1]z^{-1} + g[2]z^{-3} + g[3]z^{-3}$$

$$H(z) = h[0] + h[1]z^{-1} + h[2]z^{-3} + h[3]z^{-3}$$

$$Y_L(z) = X(z)H(z)$$

$$= y_L[0] + y_L[1]z^{-1} + y_L[2]z^{-3} + y_L[3]z^{-3} + y_L[4]z^{-4} + y_L[5]z^{-5} + y_L[6]z^{-6}$$



3.2 Circular Convolution

Example 1:

• Where $y_L[0] = g[0]h[0]$

$$y_L[1] = g[0]h[1] + g[1]h[0]$$

$$y_L[2] = g[0]h[2] + g[1]h[1] + g[2]h[0]$$

$$y_L[3] = g[0]h[3] + g[1]h[2] + g[2]h[1] + g[3]h[0]$$

$$y_L[4] = g[1]h[3] + g[2]h[2] + g[3]h[1]$$

$$y_L[5] = g[2]h[3] + g[3]h[2]$$

$$y_L[6] = g[3]h[3]$$

• Then $Y_C(z) = \langle Y_L(z) \rangle_{(z^{-4}-1)}$



on

3.2 Circular Convolution

Example 1:

$$\begin{split} Y_C(z) &= y_L[0] + y_L[1]z^{-1} + y_L[2]z^{-2} + y_L[3]z^{-3} + y_L[4] + y_L[5]z^{-1} + y_L[6]z^{-2} \\ &= \left(y_L[0] + y_L[4]\right) + \left(y_L[1] + y_L[5]\right)z^{-1} + \left(y_L[2] + y_L[6]\right)z^{-2} + y_L[3]z^{-3} \\ &= y_C[0] + y_C[1]z^{-1} + y_C[2]z^{-2} + y_C[3]z^{-3} \end{split}$$

where

$$\begin{aligned} y_C[0] &= y_L[0] + y_L[4] = g[0]h[0] + g[1]h[3] + g[2]h[2] + g[3]h[1] \\ y_C[1] &= y_L[1] + y_L[5] = g[0]h[1] + g[1]h[0] + g[2]h[3] + g[3]h[2] \\ y_C[2] &= y_L[2] + y_L[6] = g[0]h[2] + g[1]h[1] + g[2]h[0] + g[3]h[3] \\ y_C[3] &= y_L[3] = g[0]h[3] + g[1]h[2] + g[2]h[1] + g[3]h[0] \end{aligned}$$