Introduction to Channel Coding

I. Error control coding (overview)

- Shannon showed that reliable communications can be achieved by proper coding of information to be transmitted provided that the rate of information transmission is below the channel capacity.
- Coding is achieved by adding properly designed redundancy to each message before its transmission. The added redundancy is used for error control. *The redundancy may appear in the form of extra symbols (or bits), or in the form of channel signal-set expansion or in the form of combination of both.*
- Coding may be designed and performed separately from modulation, or designed in conjunction with modulation as a single entity. In the former case, redundancy appears in the form of extra symbols, normally called parity-check symbols.
- Coding achieved by adding extra redundant digits is known as *conventional coding*, in which error control (or coding gain) is achieved at the expense of bandwidth expansion or data rate reduction. Therefore, conventional coding is suitable for error control in power limited channels, such as deep space channel.
- In the case that coding is designed in conjunction with modulation, redundancy comes from channel signal-set expansion. This combination of coding and modulation is usually known as *coded modulation*, which allows us to achieve error control (or coding gain) without compromising bandwidth efficiency. We refer this technique as the bandwidth efficient coding.

Historical notes:

Hamming codes (1950)

Reed-Muller codes (1954)

BCH codes (by Bose, Ray-Chaudhuri and Hocquenghem, 1959) Reed-Solomon codes (1960)

Low-density parity-check codes (by Gallager in 1962, rediscovered in 90's)

Convolutional codes (by Elias, 1955)

Viterbi algorithm (1967)

Concatenated codes (by Forney, 1966)

Trellis-coded modulation (by Ungerboeck, 1982)

Turbo codes (by Berrou, 1993)

Space-time codes (by Vahid Tarokh, 1998)

■ Applications:

Deep space, satellite, mobile communications, voice modem, data networks, etc.

■ Two simple examples:

Repetition codes:
$$\begin{array}{c}
0 \to 000000 \\
1 \to 111111
\end{array}$$
 (n, 1) code

Single parity-check codes:

■ References:

- [1] Shu Lin and D. J. Costello, Jr. *Error Control Coding: Fundamentals and Applications*. 2nd ed. Prentice-Hall, 2004.
- [2] 王新梅, 肖国镇. 纠错码一原理与方法. 西安: 西安电子科技大学出版社, 1991.
- [3] D. J. Costello, J. Hagenauer, H. Imai, and S. B. Wicker, "Applications of error-control coding," *IEEE Trans. Inform. Theory*, vol.44, no.6, pp.2531-2560, Oct. 1998.
- [4] D. J. Costello and G. D. Forney, "Channel coding: The road to channel capacity," *Proceedings of The IEEE*, vol.95, no.6, pp.1150-1177, June 2007.

II. Block coding

■ In block coding, information sequence is divided into messages of k information bits (or symbols) each. Each message is mapped into a structured sequence of n bits (with n > k), called a codeword.

$$\underbrace{(u_0, u_1, \cdots, u_{k-1})}_{\text{message}} \longleftrightarrow \underbrace{(c_0, c_1, \cdots, c_{n-1})}_{\text{codeword}}$$

- The mapping operation is called encoding. Each encoding operation is independent of past encodings. The collection of all codewords is called an (n, k) block code, where n and k are the length and dimension of the code, respectively.
- In the process of encoding, n-k redundant bits are added to each message for protection against transmission errors.
- For example, consider a (5,2) binary code of size $M=2^k=4$:

$$00 \leftrightarrow 10101 = \mathbf{c}_1$$

$$01 \leftrightarrow 10010 = \mathbf{c}_2$$

$$10 \leftrightarrow 10010 = \mathbf{c}_3$$

$$11 \leftrightarrow 11110 = \mathbf{c}_4$$

$$\mathcal{C} = {\mathbf{c}_1, \mathbf{c}_2, \mathbf{c}_3, \mathbf{c}_4}$$

■ An important class of block codes is the class of linear block codes. A block code is said to be linear if the vector sum of two codewords is also a codeword:

$$\mathbf{c}_{i} = (c_{i,0}, c_{i,1}, \cdots c_{i,n-1}) \in \mathcal{C}, \quad \mathbf{c}_{j} = (c_{j,0}, c_{j,1}, \cdots c_{j,n-1}) \in \mathcal{C}$$

$$\mathbf{c}_{i} \oplus \mathbf{c}_{i} = (c_{i,0} \oplus c_{i,0}, c_{i,1} \oplus c_{i,1}, \cdots, c_{i,n-1} \oplus c_{i,n-1}) \in \mathcal{C}$$

More general, a linear code is a subspace of $GF(q)^n$. (矢量加、标量乘运算封闭)

■ *Linear block codes* are normally put in systematic form:

$$(c_0, c_1, \dots, c_{n-1}) = \underbrace{(c_0, c_1, \dots, c_{n-k-1}, \underbrace{u_0, u_1, \dots, u_{k-1}}_{\textit{message part}})}_{\textit{parity-check part}} \underbrace{u_0, u_1, \dots, u_{k-1}}_{\textit{message part}})$$

■ Each parity-check bit is a linear sum of message bits, i,e,

$$c_j = \sum_{i=0}^{k-1} p_{ij} u_i, \quad j = 0, 1, \dots, n-k-1.$$

where p_{ij} =0 or 1. The n-k equations which gives the parity-check bits are called the **parity-check equations**. They specify the encoding rule.

 \blacksquare For an (n, k) block code, the ratios

$$R = \frac{k}{n}$$
 and $\eta = \frac{n-k}{n}$

are called *code rate* and redundancy, respectively.

An example for block code:

Let n=7 and k=4. Consider the (7, 4) linear systematic block code

Message:
$$(u_0, u_1, u_2, u_3)$$

Codeword:
$$(c_0, c_1, c_2, c_3, c_4, c_5, c_6) = (c_0, c_1, c_2, u_0, u_1, u_2, u_3)$$

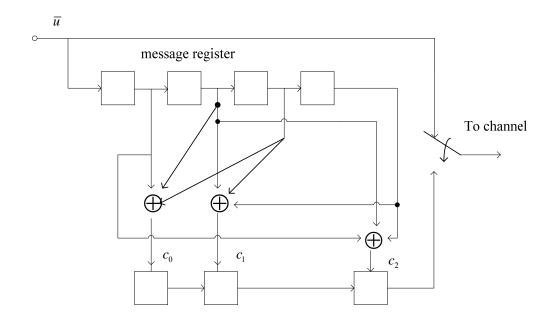
$$c_0 = u_0 + u_1 + u_2$$
 Here,
$$c_1 = u_1 + u_2 + u_3$$

$$c_2 = u_0 + u_1 + u_3$$

In matrix form:

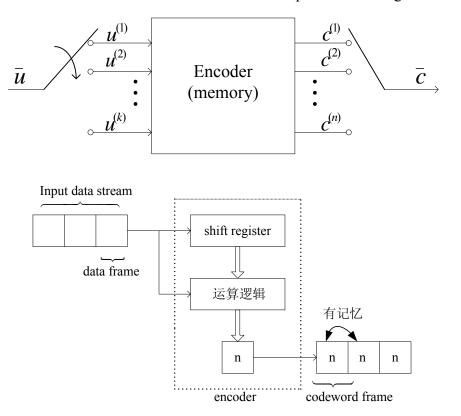
$$\mathbf{c} = (u_0, u_1, u_2, u_3) \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{u} \cdot \mathbf{G}$$

Encoder circuit:



III. Convolution Coding

- **D** During each unit of time, the input to convolutional is also a k-bit message block and the corresponding is also an n-bit coded with k < n. (为避免混淆,可改为用 $\frac{k_0}{k_0}$, $\frac{n_0}{k_0}$ 表示)
- \blacksquare Each coded *n*-bit output block depends not only on the corresponding *k*-bit input message block at the same time unit but also on the *m* previous message blocks.

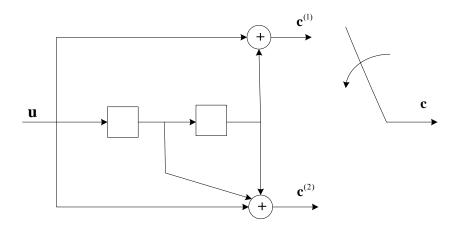


The code rate is defined as R = k / n. The parameter m is called the memory order of the code.

- In the process of coding, the information sequence \mathbf{u} is divided into data frames of length k. These subsequences of length k are applied to the k-input terminals of the encoder, producing coded sequence of length n.
- An example:

Let n=2, k=1 and m=2. Consider a rate-1/2 (2,1,2) convolutional code which is specified by the following two generator sequences:

$$\mathbf{g}^{(1)} = (101), \ \mathbf{g}^{(2)} = (111)$$



Note: $\mathbf{g}^{(1)}$, $\mathbf{g}^{(2)}$ 可看作编码器的两个冲激响应,由 $\mathbf{u} = \delta = (100...)$ 得到。冲激响应至多持续m+1个时间单位,且可写为:

$$\mathbf{g}^{(1)} = \left(g_0^{(1)}, g_1^{(1)}, \dots, g_m^{(1)}\right), \mathbf{g}^{(2)} = \left(g_0^{(2)}, g_1^{(2)}, \dots, g_m^{(2)}\right)$$

- Let $\mathbf{u} = (u_0, u_1, \cdots)$ be the input message sequence. Then the two output sequences are

$$\left. \begin{array}{l} \mathbf{c}^{(1)} = \mathbf{u} * \mathbf{g}^{(1)} \\ \mathbf{c}^{(2)} = \mathbf{u} * \mathbf{g}^{(2)} \end{array} \right\}$$
编码方程 (与冲激响应的卷积运算)

- At the *l*th time unit, the input is a single bit u_l . The corresponding output is a block of two bits, $(c_l^{(1)}, c_l^{(2)})$, which is given by

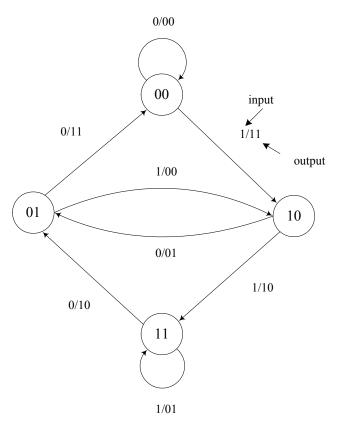
$$c_{l}^{(j)} = \sum_{i=1}^{m} u_{l-i} g_{i}^{(j)} = u_{l} g_{0}^{(j)} + u_{l-1} g_{1}^{(j)} + \dots + u_{l-m} g_{m}^{(j)}$$

$$\Rightarrow \begin{cases} c_l^{(1)} = u_l + u_{l-2} \\ c_l^2 = u_l + \underbrace{u_{l-1} + u_{l-2}}_{memory} \end{cases}$$

- The output codeword is given by $\mathbf{c} = (c_0^{(1)}c_0^{(2)}, c_1^{(1)}c_1^{(2)}, \cdots)$.

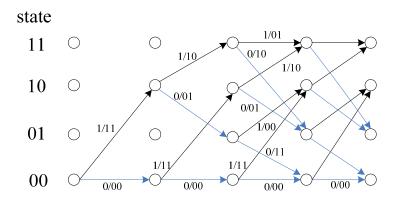
For
$$\mathbf{u} = (1011100\cdots), \mathbf{c} = (11,01,00,10,01,10,11,\cdots)$$

- <u>State Diagram:</u> Since the encoder is a linear sequential circuit, its behavior can be described by a state diagram. The encoder state at time *l* is represented by the message bits stored in the memory units.
- The encoder of the (2, 1, 2) convolutional code given in the example has 4 possible states, and its state diagram is shown in the figure below.



label = input/output

■ <u>Trellis diagram</u>: The state diagram can be expanded in time to display the state transition of a convolutional encoder in time. This expansion in time results in a trellis diagram.



- The encoding of a message sequence **u** is equivalent to tracing a path through the trellis.
- The trellis structure is very useful in decoding a convolutional code.

IV. Conventional Coding

1. Types of codes

| block codes - linear codes, cyclic codes | classification based on structure | convolutional codes |

random-error-correcting codes burst-error-correcting codes

Binary codes

Nonbinary codes

error-correction codes error-detection codes

2. Error correcting capacity

- The error correcting capacity of a code C depends on its distance structure.
- The *Hamming distance* between two codewords, \mathbf{x} and \mathbf{y} , in a code, denoted by $d_{H}(\mathbf{x}, \mathbf{y})$, is defined as the number of places in which they differ.

$$d_{H}(\mathbf{x}, \mathbf{y}) = \sum_{i=1}^{n} d_{H}(x_{i}, y_{i}), \quad d_{H}(x_{i}, y_{i}) = \begin{cases} 1, & \text{if } x_{i} \neq y_{i} \\ 0, & \text{if } x_{i} = y_{i} \end{cases}$$
or $d_{H}(\mathbf{x}, \mathbf{y}) = |\{i : x_{i} \neq y_{i}\}|$

For example, $d_H(010,111) = 2$, $d_H(30102,21103) = 3$

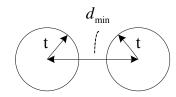
- Hamming distance satisfies the axioms for a distance metric:
 - 1) $d_H(\mathbf{x}, \mathbf{y}) \ge 0$, with equality iff $\mathbf{x} = \mathbf{y}$
 - 2) $d_H(\mathbf{x}, \mathbf{y}) = d_H(\mathbf{y}, \mathbf{x})$ (对称性)
 - 3) $d_H(\mathbf{x}, \mathbf{y}) \le d_H(\mathbf{x}, \mathbf{z}) + d_H(\mathbf{z}, \mathbf{y})$
- The minimum Hamming distance of a code C is defined as

$$d_{\min} \triangleq \min \left\{ d_H(\mathbf{x}, \mathbf{y}) \,|\, \mathbf{x}, \mathbf{y} \in \mathcal{C}, \mathbf{x} \neq \mathbf{y} \right\}$$

- For a convolutional code, this minimum Hamming distance is usually called the minimum free distance, denoted by d_{free} .
- An (n, k) block code with minimum Hamming distance d_{min} is capable of correcting

 $t = \left| \frac{d_{\min} - 1}{2} \right|$ or fewer random errors over a block of *n* digits (using minimum distance

decoding rule). This parameter t is called the error correcting capacity of the code.



decoding sphere $d_{\min} \ge 2t + 1$

■ The minimum Hamming distance of a linear block code depends on the choice of parity-check equations and the number of parity bits, n-k.

3. Important codes

- 1) Algebraic block codes
 - Hamming codes
- BCH codes: A large class of powerful multiple random error-correcting codes, rich in algebraic structure, algebraic decoding algorithms available.
- Golay (23, 12) code: A perfect triple-error-correcting code, widely used and generated by

$$g(x) = 1 + x^2 + x^4 + x^5 + x^6 + x^{10} + x^{11}$$

- Reed-Muller codes
- Reed-Solomon codes: nonbinary, correcting symbol errors or burst errors ,most widely used for error control in data communications and data storages.
- 2) Convolutional codes: (2, 1, 6) code generated by

$$\mathbf{g}^{(1)} = (1101101), \ \mathbf{g}^{(2)} = (1001111)$$

This code has $d_{\text{free}} = 10$.

3) Codes (defined) on graphs:

Low-density parity-check codes
Turbo codes

Turbo codes

4. Types of error control schemes

- Forward-error-correction (FEC): An error-correction code is used.
- Automatic-repeat-request (ARQ): An error-detection code is used.

If the presence of error is detected in a received word, a retransmission is requested. The request signal is sent to the transmitter through a <u>feedback channel</u>. Retransmission continues until no errors being detected.

- Hybrid ARQ: A proper combination of FEC and ARQ.

5. Decoding

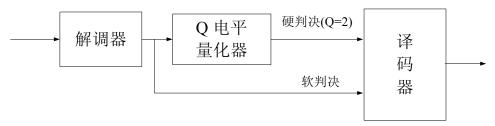
■ Based on the received sequence, the encoding rules and the noise characteristics of the channel, the receiver makes a decision which message was actually transmitted. This decision making operation is called decoding.

■ Hard-decision

When binary coding is used, the modulator has only binary inputs (M=2). If binary demodulator output quantization is used (Q=2), the decoder has only binary inputs. In this case, the demodulator is said to make hard decision. Decoding based on hard decisions made by the demodulator is called *hard-decision decoding*.

■ Soft-decision

If the output of demodulator consists of more than two quantization levels (Q>2) or is left unquantized, the demodulator is said to make soft decisions. Decoding based on this is called *soft-decision decoding*.



■ Hard-decision decoding is much easier to implement than soft-decision decoding. However, soft-decision decoding offers significant performance improvement over hard-decision decoding. See figure 2.

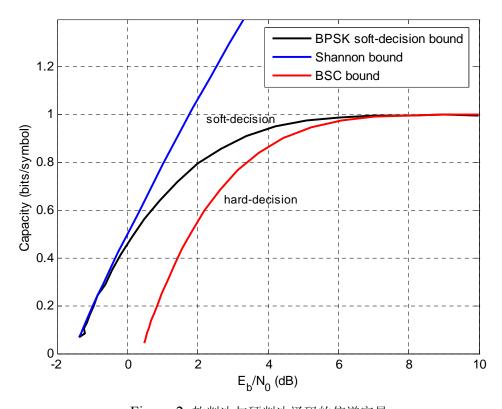


Figure 2 软判决与硬判决译码的信道容量

Optimal decoding

Given that y is received, the conditional error probability of decoding is defined as

$$P(E|\mathbf{y}) \triangleq P(\hat{\mathbf{c}} \neq \mathbf{c}|\mathbf{y})$$

Then the error probability of

$$P(E) = \sum_{\mathbf{y}} P(E \, \big| \mathbf{y}) P(\mathbf{y})$$

A decoding rule that minimizes P(E) is referred to as an optimal decoding rule.

Since minimize $P(\hat{\mathbf{c}} \neq \mathbf{c} | \mathbf{y})$ is equivalent to maximize $P(\hat{\mathbf{c}} = \mathbf{c} | \mathbf{y})$, we have

MAP rule:
$$\hat{\mathbf{c}} = \arg \max_{\mathbf{c}} P(\mathbf{c} | \mathbf{y})$$

Maximum-likelihood decoding (MLD):

Note that
$$P(\mathbf{c}|\mathbf{y}) = \frac{P(\mathbf{c})P(\mathbf{y}|\mathbf{c})}{P(\mathbf{y})}$$
, we have

ML rule: $\hat{\mathbf{c}} = \arg \max_{\mathbf{c}} P(\mathbf{y} \mid \mathbf{c})$ (Suppose all the messages are equally likely)

6. MLD for a BSC

In coding for a BSC, every codeword and every received word are binary sequences.

Suppose some codeword is transmitted and the received word is $\mathbf{y} = (y_1, y_2, ..., y_n)$.

For a codeword \mathbf{c}_i , the conditional probability $P(\mathbf{y} | \mathbf{c}_i)$ is

$$P(\mathbf{y} \mid \mathbf{c}_i) = p^{d_{\mathrm{H}}(\mathbf{y}, \mathbf{c}_i)} (1 - p)^{n - d_{\mathrm{H}}(\mathbf{y}, \mathbf{c}_i)}$$

For p < 1/2, $P(\mathbf{y} | \mathbf{c}_i)$ is a monotonially decreasing function of $d_H(\mathbf{y}, \mathbf{c}_i)$. Then

$$P(\mathbf{y} | \mathbf{c}_i) > P(\mathbf{y} | \mathbf{c}_j)$$
 iff $d_{\mathrm{H}}(\mathbf{y}, \mathbf{c}_i) < d_{\mathrm{H}}(\mathbf{y}, \mathbf{c}_j)$

- MLD:
 - 1) Compute $d_{\mathrm{H}}(\mathbf{y}, \mathbf{c}_i)$ for all $\mathbf{c}_i \in \mathcal{C}$.
 - 2) \mathbf{c}_i is taken as the transmitted codeword if $d_{\mathrm{H}}(\mathbf{y}, \mathbf{c}_i) < d_{\mathrm{H}}(\mathbf{y}, \mathbf{c}_j)$ for $\forall j \neq i$.
 - 3) Decoding \mathbf{c}_i into message \mathbf{u}_i .

This is called the *minimum distance* (nearest neighbor) decoding.

7. Performance measure and coding gain

- Block-error probability: It is the probability that a decoded word is in error.
- Bit-error probability: It is the probability that a decoded bit is in error.
- The usual figure of merit for a communication system is the ratio of energy per information bit to noise power spectral density, E_b/N_0 , that is required to achieve a

given error probability.

Coding gain of a coded communication system over an uncoded system with the same modulation is defined the reduction, expressed in dB, in the required E_b/N_0 to achieve a target error probability.

Coding gain =
$$\left[\frac{E_b}{N_0}\right]_{uncoded} - \left[\frac{E_b}{N_0}\right]_{coded}$$
 (in dB)

Shannon limit: A theoretical limit on the minimum SNR required for coded system with code rate R_c to achieve error-free information transmission. See figures 3 and 4.

V. Finite Fields (分组码的代数结构)

1. Binary arithmetic and field

Consider the binary set $\{0,1\}$, Define two binary operations, called addition '+' and multiplication '.', on $\{0,1\}$ as follows

+	0	1
0	0	1
1	1	0

•	0	1
0	0	0
1	0	1

- These two operations are commonly called module-2 addition and multiplication respectively. They can be implemented with an XOR and an AND gate, respectively.
- The set $\{0, 1\}$ together with module-2 addition and multiplication is called a binary field, denoted by GF(2) or \mathbb{F}_2 .

2. Vector space over GF(2)

- A binary *n*-tuple is an ordered sequence, $(a_1, a_2, ..., a_n)$, with $a_i \in GF(2)$.
 - There are 2^n distinct binary n-tuples.
 - Define an addition operation for any two binary *n*-tuples as follows:

$$(a_1, a_2, ..., a_n) + (b_1, b_2, ..., b_n) = (a_1 + b_1, a_2 + b_2, ..., a_n + b_n)$$

where a_i+b_i is carried out in module-2 addition.

- Define a scalar multiplication between and element c in GF(2) and a binary n-tuple $(a_1,a_2,...,a_n)$ as follows:

$$c \cdot (a_1, a_2, ..., a_n) = (c \cdot a_1, c \cdot a_2, ..., c \cdot a_n)$$

where $c \cdot a_i$ is carried out in module-2 multiplication.

- Let V^n denote the set of all 2^n binary n-tuples. The set V^n together with the addition defined for any two binary n-tuples in V^n and the scalar multiplication is called a vector space over GF(2). The elements in V^n are called vectors.
 - Note that V^n contains the all-zero *n*-tuple (0,0,...,0) and

$$(a_1, a_2, ..., a_n) + (a_1, a_2, ..., a_n) = (0, 0, ..., 0)$$

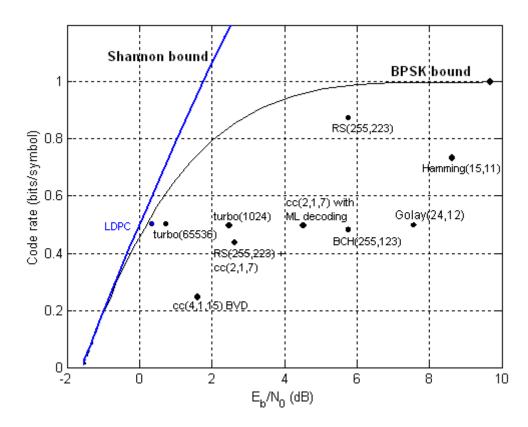


Figure 3 Milestones in the drive towards channel capacity achieved over the past 50 years.

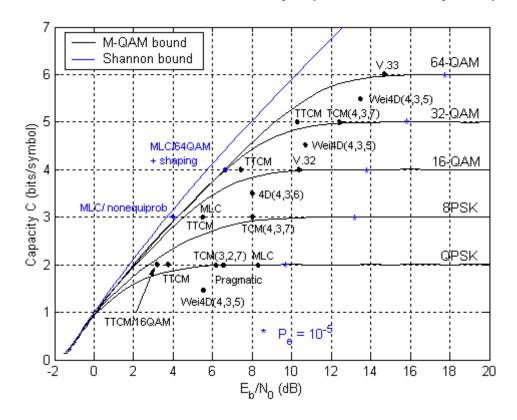


Figure 4 Performance of various coded modulation schemes.

 \blacksquare Example: Let n=4. Then

$$V^4 = \begin{cases} (0000), (0001), (0010), (0011), (0100), (0101), (0110), (0111) \\ (1000), (1001), (1010), (1011), (1100), (1101), (1110), (1110) \end{cases}$$

- A subset S of V^n is called a subspace of V^n if
 - 1) the all-zero vector is in S;
 - 2) the sum of two vectors in S is also a vector in S;

For example: $S=\{(0000),(0101),(1010),(1111)\}$ forms a subspace of V^4 .

A linear combination of k vectors, $\mathbf{V}_1, \mathbf{V}_2, ..., \mathbf{V}_k$ in \mathbf{V}^n is a vector of the form

$$\mathbf{V} = c_1 \mathbf{V}_1 + c_2 \mathbf{V}_2 + \dots + c_k \mathbf{V}_k$$

where $c_i \in GF(2)$ and is called the coefficient of V_i .

- The subspace formed by the 2^k linear combinations of k linearly independent vectors $\mathbf{V}_1, \mathbf{V}_2, ..., \mathbf{V}_k$ in V^n is called a k-dimensional subspace of V^n .
- A binary polynomial is a polynomial with coefficients from the binary field. For example, $1+x^2$, $1+x+x^3$.
 - A binary polynomial p(x) of degree m is said to be irreducible if it is not divisible by any binary polynomial of degree less than m and greater than zero. For example, $1+x+x^2$, $1+x+x^3$.
 - An irreducible polynomial p(x) of degree m is said to be **primitive** if the smallest positive integer n for which p(x) divides x^n+1 is $n=2^m-1$. For example, $p(x)=1+x+x^4$. (it divides $x^{15}+1$)
 - For any positive integer m, there exists a primitive polynomial of degree m. (可查表)

4. Galois fields

- Groups: A group is an algebraic structure (G, *) consisting of a set G and an operation * satisfying the following axioms:
 - 1) Closure: For any $a, b \in G$, the element a*b is in G;
 - 2) Associative law: For any $a, b, c \in G$, $a^*(b^*c)=(a^*b)^*c$;
 - 3) Identity element: There is an element $e \in G$ for which $e^*a=a^*e=a$ for all $a \in G$;
 - 4) Inverse: For every $a \in G$, there exists a unique element $a^{-1} \in G$, such that $a*a^{-1} = a^{-1}*a = e$.
- A group is called a commutative group or **Abelian group** if a*b = b*a for all a, b∈G. Examples: 整数,有理数,实数,with addition;
 - Integers with module-m addition.
- Fields: A field \mathbb{F} is a set that has two operations defined on it: Addition and multiplication, such that the following axioms are satisfied:
 - 1) The set is an Abelian group under addition; (单位元称为'0')

- 2) The set is closed under multiplication, and the set $\{a \in \mathbb{F}, a \neq 0\}$ forms an Abelian group (whose identity is called '1') under the multiplication (*);
- 3) Distributive law: For all a, b, $c \in \mathbb{F}$, (a+b)*c=(a*c)+(b*c).

我们经常用'0'表示加法运算下的单位元,'-a'表示 a 的加法逆。经常用'1'表示乘法运算下的单位元,'a⁻¹'表示 a 的乘法逆。这样,减法 a-b means a+(-b), 除法 a/b means b⁻¹a.

■ A field with q elements, if it exists, is called a *finite field*, or a *Galois field*, and is denoted by GF(q).

For example, GF(2)—the smallest field

- Let \mathbb{F} be a field. A subset of \mathbb{F} is called a subfield if it is a field under the inherited addition and multiplication. 原来的域 \mathbb{F} 称为 an extension field of the subfield.
- In any field, if ab=ac and $a\neq 0$, then b=c.
- For any positive integer $m \ge 1$, there exists a Galois field of 2^m elements, denoted by $GF(2^m)$.
- The construction of $GF(2^m)$ is very much the same as the construction of the complex-number field from the real-number field.

We begin with a primitive polynomial p(x) of degree m with coefficients from the binary field GF(2).

- Let α be the root of p(x); i.e., $p(\alpha)=0$. Then the field elements can be represented by $\{0,1,\alpha,\alpha^2,...,\alpha^{q-2}\}$, where $q=2^m$.

$$0 = \alpha^{-\infty}$$
, $1 = \alpha^{0}$, α^{1} , α^{2} , ..., α^{q-2} ,

 $1=\alpha^{q-1}$ (since α is a root of p(x) and $p(x) \mid x^{2^m-1}+1$, α must be a root of $x^{2^m-1}+1$)

- For example: Construct GF(4) from GF(2) using $p(x) = x^2 + x + 1$.

Polynomial notation	Binary notation	Integer	Exponential
0	00	0	0
1	01	1	1
X	10	2	α
<i>x</i> +1	11	3	α^2 $\alpha^3 = 1 = \alpha^0$

The element α whose powers generate all the nonzero elements of $GF(2^m)$ is called a *primitive element* of $GF(2^m)$.

VI. Binary Linear Block codes

- An (n, k) linear block code over GF(2) is simply a k-dim subspace of the vector space V^n of all the binary n-tuples.
- In any linear code, the all-zero word, as the vector-space origion, is always a codeword (: if \mathbf{c} is a codeword, then (- \mathbf{c}) is also a codeword, so dose \mathbf{c} +(- \mathbf{c})).
- The Hamming weight $w(\mathbf{c})$ of a vector \mathbf{c} is the number of nonzero components of \mathbf{c} . Obviously, $w(\mathbf{c}) = d_{\mathrm{H}}(\mathbf{c}, \mathbf{0})$.
- The minimum Hamming weight of a code C is the smallest Hamming weight of any nonzero codeword of C.

$$w_{\min} = \min_{\mathbf{c} \in \mathcal{C}, \mathbf{c} \neq 0} w_H(\mathbf{c})$$

For a linear code, $d_H(\mathbf{c}_1, \mathbf{c}_2) = d_H(\mathbf{0}, \mathbf{c}_2 - \mathbf{c}_1) = d_H(\mathbf{0}, \mathbf{c}) = w(\mathbf{c})$

$$d_{\min} = \min \left\{ d_H \left(\mathbf{0}, \mathbf{c}_i - \mathbf{c}_j \right) \middle| \mathbf{c}_i, \mathbf{c}_j \in \mathcal{C}, i \neq j \right\} = \min_{\mathbf{c} \neq 0} w(\mathbf{c}) = w_{\min}$$

1. Generator matrix

A generator matrix for a linear block code C of length n and dimension k is any $k \times n$ matrix G whose rows form a basis for C.

Every codeword is a linear combination of the rows of **G**.

$$\mathbf{G} = \begin{bmatrix} \mathbf{g}_0 \\ \mathbf{g}_1 \\ \vdots \\ \mathbf{g}_{k-1} \end{bmatrix} = \begin{bmatrix} g_{00} & g_{01} \cdots & g_{0,n-1} \\ g_{10} & g_{11} \cdots & g_{1,n-1} \\ \vdots \\ g_{k-1,0} & g_{k-1,1} \cdots g_{k-1,n-1} \end{bmatrix}_{k \times n}$$

Encoding procedure: $\mathbf{c} = \mathbf{u} \cdot \mathbf{G} = \begin{bmatrix} u_0, u_1, \dots u_{k-1} \end{bmatrix} \begin{bmatrix} \mathbf{g}_0 \\ \mathbf{g}_1 \\ \vdots \\ \mathbf{g}_{k-1} \end{bmatrix} = \sum_{l=0}^{k-1} u_l \mathbf{g}_l$

Example: For a (6, 3) linear block code,

$$\mathbf{G} = \begin{bmatrix} \mathbf{g}_0 \\ \mathbf{g}_1 \\ \mathbf{g}_2 \end{bmatrix} = \begin{bmatrix} 011100 \\ 101010 \\ 110001 \end{bmatrix}$$

The codeword for the message $\mathbf{u} = (101)$ is

$$\mathbf{c} = \mathbf{u} \cdot \mathbf{G} = 1 \cdot (011100) + 0 \cdot (101010) + 1 \cdot (110001) = (101101)$$

■ An (n, k) linear systematic code is completely specified by an $k \times n$ generator matrix of the following form:

$$G = \begin{bmatrix} \overline{g}_0 \\ \overline{g}_1 \\ \vdots \\ \overline{g}_{k-1} \end{bmatrix} = \begin{bmatrix} p_{00} & p_{01} \cdots p_{0,n-k-1} \\ p_{10} & p_{11} \cdots p_{1,n-k-1} \\ \vdots \\ p_{k-1,0} & p_{k-1,1} \cdots p_{k-1,n-k-1} \\ \vdots \\ p_{matrix with} & p_{ij} = 0 \text{ or } 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix} = \begin{bmatrix} P & \vdots & I_k \end{bmatrix}$$

For example, the (6, 3) code above is a systematic code:

$$c_5 = u_2$$

$$c_4 = u_1$$

$$c_3 = u_0$$

$$c_2 = u_0 + u_1$$

$$c_1 = u_0 + u_2$$

$$c_0 = u_1 + u_2$$
parity-check equations

2. Parity-check matrix

■ An (n, k) linear code can also be specified by an $(n-k)\times n$ matrix **H**.

Let $\mathbf{c} = (c_0 \ c_1 \cdots c_{n-1})$ be an *n*-tuple. Then \mathbf{c} is a codeword iff

$$\mathbf{c} \cdot \mathbf{H}^T = \mathbf{0} = \underbrace{\left(0 \ 0 \cdots 0\right)}_{n-k \uparrow}$$

The matrix **H** is called a parity-check matrix. By definition,

$$GH^T = 0$$

■ For an (n, k) linear systematic code with generator matrix $\mathbf{G} = [\mathbf{P} \ \mathbf{I}_k]$, the parity-check matrix is

$$\mathbf{H} = \begin{bmatrix} \mathbf{h}_0 \\ \mathbf{h}_1 \\ \vdots \\ \mathbf{h}_{n-k} \end{bmatrix} = \begin{bmatrix} \mathbf{I}_{n-k} \vdots - \mathbf{P}^T \end{bmatrix}$$

■ Example: For (7, 4) Hamming code

$$\mathbf{G} = \begin{bmatrix} 1101000 \\ 0110100 \\ 1110010 \\ \underline{101}0001 \end{bmatrix} \Rightarrow \mathbf{H}_{3\times7} = \begin{bmatrix} 100:1011 \\ 010:1110 \\ 001:\underline{0111} \\ \mathbf{P}^T \end{bmatrix} \Rightarrow \begin{cases} c_0 = u_0 + u_2 + u_3 \\ c_1 = u_0 + u_1 + u_2 \\ c_2 = u_1 + u_2 + u_3 \end{cases}$$

Thus, block code $C = \{ \mathbf{c} \in GF(q)^n | \mathbf{cH} = \mathbf{0} \}$.

3. Syndrome decoding

Error vector (or error pattern): Let \mathbf{c} be the transmitted codeword, and \mathbf{r} be the received word. Then the difference between \mathbf{r} and \mathbf{c} gives the pattern of errors: $\mathbf{e} = \mathbf{r} \cdot \mathbf{c}$ (for

binary codes,
$$e = r \oplus c$$
)

 e_i =1 indicates that the *j*-th position of **r** has an error.

- \blacksquare Obviously, $\mathbf{r} = \mathbf{c} + \mathbf{e}$.
- There are in total 2^n possible error patterns. Among them, only 2^{n-k} patterns are correctable by an (n, k) linear code.
- To test whether a received vector \mathbf{r} contains errors, we compute the following (n-k)-tuple:

$$\mathbf{S} = (s_0, s_1, \dots, s_{n-k-1}) \triangleq \mathbf{r} \cdot \mathbf{H}^T$$

$$= (\mathbf{c} + \mathbf{e}) \cdot \mathbf{H}^T$$

$$= \mathbf{c} \mathbf{H}^T + \mathbf{e} \mathbf{H}^T = \mathbf{e} \mathbf{H}^T$$

问题:
$$\mathbf{s} \Rightarrow \mathbf{e} = ?$$

If $\mathbf{s} \neq \mathbf{0} \Rightarrow \mathbf{e} \neq \mathbf{0}$

If
$$s=0 \Rightarrow$$
 无错, $e=0$; 或错误不可检: $e \in C$.

- The (n-k)-tuple, **s** is called the syndrome of **r**. Any method solving these n-k equations is a decoding method.
- 最小译码距离就是找重量最轻的 **e** such that $\mathbf{e}\mathbf{H}^T = \mathbf{r}\mathbf{H}^T = \mathbf{s}$
- Syndrome decoding consists of these steps:
 - 1) Calculate syndrome $\mathbf{s} = \mathbf{r}\mathbf{H}^T$ of received *n*-tuple.
 - 2) Find 最可能的错误图样 e with $eH^T = s$ ---> 非线性运算

- 3) 估计发送码字 $\hat{\mathbf{c}} = \mathbf{r} \mathbf{e}$.
- 4) Determine message $\hat{\mathbf{u}}$ from the encoding equation $\hat{\mathbf{c}} = \hat{\mathbf{u}}\mathbf{G}$.
- Example: (7, 4) Hamming code. Suppose $\mathbf{c} = (1001011)$ is transmitted and $\mathbf{r} = (1001001)$ is received. Then $\mathbf{s} = (s_0, s_1, s_2) = \mathbf{r} \mathbf{H}^T = (111)$

Let $\mathbf{e} = (e_0, e_1, ..., e_6)$ be the error pattern. Since $\mathbf{s} = \mathbf{e}\mathbf{H}^T$, we have the following 3 equations:

$$1=e_0+e_3+e_5+e_6$$

 $1=e_1+e_3+e_4+e_5$
 $1=e_2+e_4+e_5+e_6$

There are 16 possible solutions, 其中 e=(0000010)是重量最小,是最可能发生的错误图样,故 $\hat{\mathbf{c}} = \mathbf{r} \oplus \mathbf{e} = (10010010) \oplus (0000010) = (1001011)$.

Standard array

$\mathbf{c}_1 = 0$	\mathbf{c}_2	\mathbf{c}_3	•••	\mathbf{c}_{M}
\mathbf{e}_2	$e_2 + c_2$	$e_2 + c_3$	•	$\mathbf{e}_2 + \mathbf{c}_M$
e ₃	e_3+c_2	$e_3 + c_3$	•••	$\mathbf{e}_3 + \mathbf{c}_M$
•••	•••	•••	•••	•••
\mathbf{e}_{2^r}	$\mathbf{e}_{2^r} + \mathbf{c}_2$	$\mathbf{e}_{2^r} + \mathbf{c}_3$	•••	$\mathbf{e}_{2^r} + \mathbf{c}_M$

$$M=2^k$$
, $r=n-k$

- Each row is called a *coset*.

4. Hamming codes

- First class of codes devised for error correction.
- For any positive integer $m \ge 3$, there exists a Hamming code with the following parameters:

code length:
$$n = 2^m - 1$$

dimension:
$$k = 2^m - m - 1$$

Error correcting capability: t=1 Minimum distance: $d_{min}=3$

Note: A field is a set of elements (or symbols) in which we can do addition, subtraction, multiplication, and division without leaving the set. Addition and multiplication satisfy the communicative, associative and distributive laws.

Examples: real-number field, complex-number field

Galois, Evariste

Galois (1811~1832) 生于 BourgLa Reine (巴黎近郊), 卒于巴黎, 法国代数学家。 发明 Galois 理论,与 Abel 并称为现代群论的创始人。 他们俩的早殇,是十九世纪数学界的悲剧。

Galois 的父母都是知识分子, 12 岁以前, Galois 的教育全部由他的母亲负责, 他的父亲在 Galois 4 岁时被选为 Bourg La Reine 的市长。

12岁, Galois 进入路易皇家中学就读, 成绩都很好, 却要到 16岁才开始跟随 Vernier 老师学习数学, 他对数学的热情剧然引爆, 对于其他科目再也提不起任何兴趣。 校方描述此时的 Galois 是「奇特、怪异、有原创力又封闭」。

1827年,16岁的Galois 自信满满地投考他理想中的(学术的与政治的)大学:综合工科学校(Ecole Polytechnique),却因为颟顸无能的主考官而名落孙山。

1829年,Galois 将他在代数方程解的结果呈交给法国科学院,由 Cauchy 负责审阅,Cauchy 却将文章连同摘要都弄丢了(19世纪的两个短命数学天才 Abel 与 Galois 不约而同地都「栽」在 Cauchy 手中)。

更糟糕的是,当 Galois 第二次要报考综合工科大学时,他的父亲却因为被人在选举时恶意中伤而自杀。 正直父亲的冤死,影响他考试失败,也导致他的政治观与人生观更趋向极端。

Galois 进入高等师范学院(Ecole Normale Supérieure)就读,次年他再次将方程式论的结果,写成三篇论文,争取当年科学院的数学大奖,但是文章在送到 Fourier 手中后,却因 Fourier 过世又遭蒙尘,Galois 只能眼睁睁看着大奖落入 Abel 与 Jacobi 的手中。

1830年七月革命发生,保皇势力出亡,高等师范校长将学生锁在高墙内,引起 Galois 强烈不满,十二月 Galois 在校报上抨击校长的作法,因此被学校退学。由于强烈支持共和主义,从 1831年五月后,Galois 两度因政治原因下狱,也曾企图自杀。

1832年三月他在狱中结识一个医生的女儿并陷入狂恋,接下来是他那传奇的死亡:因为这段感情,他陷入一场决斗,自知必死的 Galois 在决斗前夜将他的所有数学成果狂笔疾书纪录下来,第二天他果然在决斗中死亡。

他的朋友 Chevalier 遵照 Galois 的遗愿,将他的数学论文寄给高斯与 Jacobi,但是都石沉大海,要一直到 1843 年,才由 Liouville 肯定 Galois 结果之正确、独创与深邃,并在 1846 年将它发表。

(撰稿: 翁秉仁/台大數學系)